Equations of motion

Friday, November 3, 2017

For the glory of God

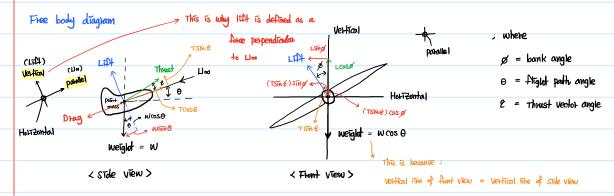
Assumptions

- · An aircraft is represented as a moving point mass.
- There is no side stip.

 S Geomethy is collapsed to a point. In a point mass analysis, we only think about the output

(e.g. Do not case about area but case about Co.o)

· Therefore, we don't care about both Aerodynamics (e.g. Aerodynamic center) and Stability (e.g. pitch angle effect)



Equations of motion

· Let's apply Newton's 2 ND law to each direction: Parallel. Vertical, and horizontal

Is when you think about it, please come up with Aighot hand, tule.

The force is the time rate of momentum change;

$$\frac{1}{F} = \frac{d}{dt} (m\frac{1}{r})$$

$$= \frac{d}{dt} (m\frac{1}{r}) + m \frac{d\frac{1}{r}}{dt}$$

o (: we are now looking into the snapshot of the flying)

· When it comes to Parallel direction, (please see the stide view)

 \Leftrightarrow TCOS ε - D - WSTIN θ = M $\frac{d \, \Box_{M}}{d t}$; where \Box_{M} = General expression at this point

· Aegarding Vertical direction, (please see the flont view)

$$rac{1}{r} = m \frac{d\hat{u}}{dt}$$

 $\Leftrightarrow L\cos \phi - w\cos \theta + T\sin \theta \cos \phi = \frac{u}{R}$

